## Molecular Dynamics

## Goal: trajectories $x(t)$ that sample the different conformations of the system so that we can calculate correct thermodynamic observables.

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## Molecular Dynamics Algorithm

- equations of motion for $N$ particles

$$
\mathbf{F}_{i}=m_{i} \mathbf{a}_{i}=m_{i} \frac{d^{2} \mathbf{r}}{d t^{2}}=m_{i} \ddot{\mathbf{r}}_{i}
$$

- potential energy

$$
U\left(\mathbf{r}_{1}, \ldots, \mathbf{r}_{N}\right)=U_{\text {bonded }}\left(\left\{\mathbf{r}_{i}\right\}\right)+U_{\text {nonbonded }}\left(\left\{\mathbf{r}_{i}\right\}\right.
$$

$$
\begin{aligned}
& U_{\text {elec }}\left(\mathbf{r}_{j}, \mathbf{r}_{k}\right)=\frac{1}{4 \pi \epsilon_{0}} \frac{q_{j} q_{k}}{\left|\mathbf{r}_{j}-\mathbf{r}_{k}\right|} \\
& U_{\mathrm{vdW}}\left(\mathbf{r}_{j}, \mathbf{r}_{k}\right)=4 \varepsilon\left[\left(\frac{\sigma}{r_{j k}}\right)^{12}-\left(\frac{\sigma}{r_{j k}}\right)^{6}\right]
\end{aligned}
$$

- forces

$$
\mathbf{F}_{i}=-\nabla_{i} U\left(\mathbf{r}_{1}, \ldots, \mathbf{r}_{i}, \ldots, \mathbf{r}_{N}\right)
$$

# Basic MD program 

initialize()
$t=0$
while $t<t_{\text {max }}$

$$
\begin{aligned}
& \mathbf{f}=\text { forces }(\mathbf{r}) \\
& \mathbf{r}=\text { integrate }(\mathbf{r}, \mathbf{f}) \\
& \text { write_trajectory }(\mathbf{r}) \\
& t=t+d t
\end{aligned}
$$

## Basic workflow

I. prepare starting conformation
2. run equilibration
3. run production

- compute estimators for observables $a(\mathbf{r}, \mathbf{v})$
- save trajectory ( $\mathbf{r}$, maybe $\mathbf{V}$ and $\mathbf{F}$ )

4. analyse trajectory/output files

## Force calculation

initialize()
$t=0$
while $t<t_{\text {max }}$

$$
\begin{aligned}
& \mathbf{f}=\text { forces }(\mathbf{r}) \\
& \mathbf{r}=\text { integrate }(\mathbf{r}, \mathbf{f}) \\
& \text { write_trajectory }(\mathbf{r}) \\
& t=t+d t
\end{aligned}
$$

## Force calculation

$$
\mathbf{F}_{i}=-\nabla_{i} U\left(\mathbf{r}_{1}, \ldots, \mathbf{r}_{i}, \ldots, \mathbf{r}_{N}\right)
$$

For pair-potentials $v\left(\left|\mathbf{r}_{j}-\mathbf{r}_{i}\right|\right)=v\left(r_{j}\right)$


$$
\mathbf{F}_{j}=\sum_{i} \underbrace{\left[-\nabla_{i} v\left(r_{i j}\right)\right]}_{\mathbf{f}_{i j}}=-\sum_{i} \frac{\mathbf{r}_{i j}}{r_{i j}} \frac{\partial}{\partial r_{i j}} v\left(r_{i j}\right)
$$

$$
\mathbf{f}_{i j}=-\mathbf{f}_{j i} \quad \text { (Newton's 3rd law) }
$$



## Lennard-Jones Potential

$$
\begin{aligned}
& v\left(r_{i j}\right)=4 \epsilon\left[\left(\frac{\sigma}{r_{i j}}\right)^{12}-\left(\frac{\sigma}{r_{i j}}\right)^{6}\right] \\
& \mathbf{f}\left(r_{i j}\right)=-24 \epsilon \frac{\mathbf{r}_{j i}}{r_{i j}^{2}}\left[2\left(\frac{\sigma}{r_{i j}}\right)^{12}-\left(\frac{\sigma}{r_{i j}}\right)^{6}\right]
\end{aligned}
$$



# Integrating the Equations of Motion 

initialize()
$t=0$
while $t<t_{\text {max }}$

$$
\begin{aligned}
& \mathbf{f}=\text { forces }(\mathbf{r}) \\
& \mathbf{r}=\text { integrate }(\mathbf{r}, \mathbf{f}) \\
& \text { write_trajectory }(\mathbf{r}) \\
& t=t+d t
\end{aligned}
$$

# Integrating the Equations of Motion 

$$
m_{i} \ddot{\mathbf{r}}_{i}=\mathbf{F}_{i}
$$

- have forces $\mathbf{F}_{i}$ and current positions $\mathbf{r}_{i}(t)$
- want: positions $\mathbf{r}_{i}(t+\Delta t)$


## Velocity Verlet Integrator

$$
\begin{align*}
\mathbf{v}\left(t+\frac{\Delta t}{2}\right) & =\mathbf{v}(t)+\frac{\Delta t}{2} \frac{\mathbf{F}(t)}{m}  \tag{1}\\
\mathbf{r}(t+\Delta t) & =\mathbf{r}(t)+\Delta t \mathbf{v}\left(t+\frac{\Delta t}{2}\right)  \tag{2}\\
\mathbf{v}(t+\Delta t) & =\mathbf{v}\left(t+\frac{\Delta t}{2}\right)+\frac{\Delta t}{2} \frac{\mathbf{F}(t+\Delta t)}{m} \tag{3}
\end{align*}
$$

- gives both positions and velocities
- one force evaluation per time step
- see Module 10 ODEs


## Good integrators

- speed? - not very relevant
- accuracy for large time steps $\Delta t$
- energy conservation (for $\partial \mathrm{H} / \partial \mathrm{t}=0$ )
- short term
- long term (more important)
- time reversible (Newton's EOMs!)
- phase-space area preserving (Hamiltonian dynamics!)
- accurately predict the trajectories of all particles for short and long times?


## Good integrators

- speed/memory? - not very relevant
- accuracy for large time steps $\Delta t$
- energy conservation (for $\partial \mathrm{H} / \partial \mathrm{t}=0$ )
- short term
- long term (more important)
- time reversible (Newton's EOMs!)
- phase-space area preserving (Hamiltonian dynamics!)
- accurately predict the trajectories of all particles for short and long times?


## Verlet

- fast, small memory requirements
- not very high accuracy for long time steps
- fair short- and good long term energy conservation
- time reversible and area preserving ("symplectic")


## Time step



from Leach, 2001

- rule of thumb for Verlet-type integrators: 5 steps per period (typically I-2 fs in biomolecular systems)


## Time step





## Thermodynamic observables

- Macroscopic thermodynamic quantities (temperature $T$, pressure $P$, volume $V$, particle number $N$, heat capacities, dipole moments, magnetization, ...) can be written as averages over functions that depend on microscopic positions and velocities ("estimator").

$$
\begin{gathered}
A=\langle a\rangle \\
A=\left\langle a\left(\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{N}, \mathbf{v}_{1}, \mathbf{v}_{2}, \ldots, \mathbf{v}_{N}\right\rangle\right. \\
A=\left\langle a\left(\mathbf{x}_{1}(t), \mathbf{x}_{2}(t), \ldots, \mathbf{x}_{N}(t), \mathbf{v}_{1}(t), \mathbf{v}_{2}(t), \ldots, \mathbf{v}_{N}(t)\right)\right\rangle_{t} \\
A=\frac{1}{N_{t}} \sum_{i=1}^{N_{t}} a\left(\mathbf{x}_{1}(t), \mathbf{x}_{2}(t), \ldots, \mathbf{x}_{N}(t), \mathbf{v}_{1}(t), \mathbf{v}_{2}(t), \ldots, \mathbf{v}_{N}(t)\right)
\end{gathered}
$$

## Energy E

$$
\begin{aligned}
E & =\langle\mathcal{H}\rangle \\
\mathcal{H} & =T_{\text {kin }}(t)+U(t) \\
& =\sum_{i=1}^{N} \frac{1}{2} m_{i} \mathbf{v}_{i}^{2}+\sum_{i<j}^{N-1} U_{\mathrm{LJ}}\left(r_{i j}\right) \\
& \quad r_{i j}:=\left|\mathbf{r}_{j}-\mathbf{r}_{i}\right|
\end{aligned}
$$

$\mathcal{H}$ :"Hamiltonian" (total instantaneous energy)
Energy conservation: $\quad \frac{d \mathcal{H}}{d t}=0$

## Temperature $T$

$$
T_{\text {kin }}(t)=\frac{1}{2} \sum_{i=1}^{N} m_{i} \mathbf{v}_{i}(t)^{2}
$$

$$
\left\langle T_{\text {kin }}\right\rangle=N \frac{3}{2} k_{B} T
$$

$\mathrm{I} / 2 \mathrm{kT}$ per degree of freedom

$$
T=\frac{2\left\langle T_{\mathrm{kin}}\right\rangle}{3 k_{B} N}
$$

## Boltzmann's constant

$$
\begin{aligned}
\mathcal{T}(t) & =\frac{2 T_{\mathrm{kin}}(t)}{3 k_{B} N} \\
T & =\langle\mathcal{T}(t)\rangle_{t}
\end{aligned}
$$

$$
A=\frac{1}{N_{t}} \sum_{i=1}^{N_{t}} a\left(\mathbf{x}_{1}(t), \mathbf{x}_{2}(t), \ldots, \mathbf{x}_{N}(t), \mathbf{v}_{1}(t), \mathbf{v}_{2}(t), \ldots, \mathbf{v}_{N}(t)\right)
$$

## Pressure P

- pressure can be derived from a version of the virial theorem (... another time)

$$
\begin{aligned}
& P V=N k_{B} T+\frac{w}{3} \\
& \text { "virial" } w:=\left\langle\sum_{i<j}^{N-1} \mathbf{r}_{i j} \cdot \mathbf{f}_{i j}\right\rangle \quad \mathbf{F}_{i}=\sum_{j \neq i} \mathbf{f}_{i j} \\
& \mathcal{P}(t)=V^{-1}\left[N k_{B} \mathcal{T}(t)+\frac{1}{3} \sum_{i<j}^{N-1} \mathbf{r}_{i j}(t) \cdot \mathbf{f}_{i j}(t)\right] \\
& P=\langle\mathcal{P}(t)\rangle_{t}
\end{aligned}
$$

## Summary

- outline of the MD algorithm
- use of periodic boundary conditions
- potential truncation
- integrators
- calculating macroscopic observables from microscopic estimators


## Appendix

## Small systems: Surface effects

- In a small system,"most" particles are "near: the surface.
- "near" = typical interaction distance $d \sim 3 \sigma$
- $N_{\text {surf }} / \mathrm{N} \sim \mathrm{N}^{-1 / 3}$
- Problem when we are interested in bulk properties.


## Small systems: Periodic boundaries


box centered on origin:

$$
\mathbf{r}_{i} \leftarrow \mathbf{r}_{i}-L \operatorname{rint}\left(\frac{\mathbf{r}_{i}}{L}\right)
$$


from Allen \& Tildesley, I 1987
$\mathbf{r}_{i j} \leftarrow \mathbf{r}_{i j}-L \operatorname{rint}\left(\frac{\mathbf{r}_{i j}}{L}\right)$

## Periodic boundaries: Potential Issues

- simulate infinite system so must handle an infinite amount of interactions (though often truncation is permissible)
- spurious correlations/ordering
- only fluctuations allowed with lattice periodicity, and max wavelength $\lambda=L$
$\Rightarrow$ phase transitions with long wavelength fluctuations problematic
- non-isotropic pair distribution function


## Periodic boundaries: Interactions

- pair wise $v\left(r_{i j}\right) \sim N^{2}$
- minimum image convention
- truncation at cutoff $R_{c}$
$v(r)$ must fall off faster than $r^{-3}$
$R_{c}<L / 2$



## Truncation of potentials

(proper periodic treatment: advanced topic)

- simple truncation $\quad u^{\text {trunc }}(r)= \begin{cases}u(r) & r \leq R_{c} \\ 0 & r>R_{c}\end{cases}$
- truncation and shift $u^{\text {shift }}(r)= \begin{cases}u(r)-u\left(R_{c}\right) & r \leq R_{c} \\ 0 & r>R_{c}\end{cases}$
- minimum image convention


## Periodic boundaries: Cells


truncated octahedron (0.77 d3)

+ cube/parallel epiped ( $d^{3}$ )
+ hexagonal prism
+ elongated rhombic dodecahedron


## Periodic boundaries: Tail correction

$$
\begin{aligned}
& U_{\text {tot }}=\frac{1}{2} N \rho \int_{0}^{\infty} u(r) g(r) 4 \pi r^{2} d r \\
& U_{\text {tot }}=\sum_{i<j} u_{c}\left(r_{i j}\right)+\frac{1}{2} N \rho \int_{R_{c}}^{\infty} u(r) 4 \pi r^{2} d r \\
& u_{c}(r)= \begin{cases}u(r) & \begin{array}{l}
r \leq R_{c} \\
0 \\
r>R_{c}
\end{array} \\
g(r) \approx 1 & \text { for } \underline{r>R_{c}}\end{cases}
\end{aligned}
$$

## Verlet Integrator

$$
\mathbf{r}(t+\Delta t) \approx 2 \mathbf{r}(t)-\mathbf{r}(t-\Delta t)+\frac{\mathbf{F}(t)}{m} \Delta t^{2}
$$

- no velocities needed
- same accuracy as velocity Verlet
- velocities can be computed (but $\mathcal{O}\left(\Delta t^{2}\right)$ )

$$
\mathbf{v}(t)=\frac{\mathbf{r}(t+\Delta t)-\mathbf{r}(t-\Delta t)}{2 \Delta t}+\mathcal{O}\left(\Delta t^{2}\right)
$$

