

# 09 Molecular Dynamics

Goal: **trajectories  $x(t)$**  that sample the different conformations of the system so that we can calculate correct **thermodynamic observables**.

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# Molecular Dynamics Algorithm

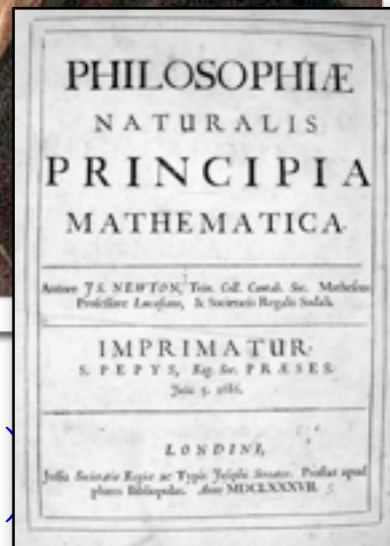
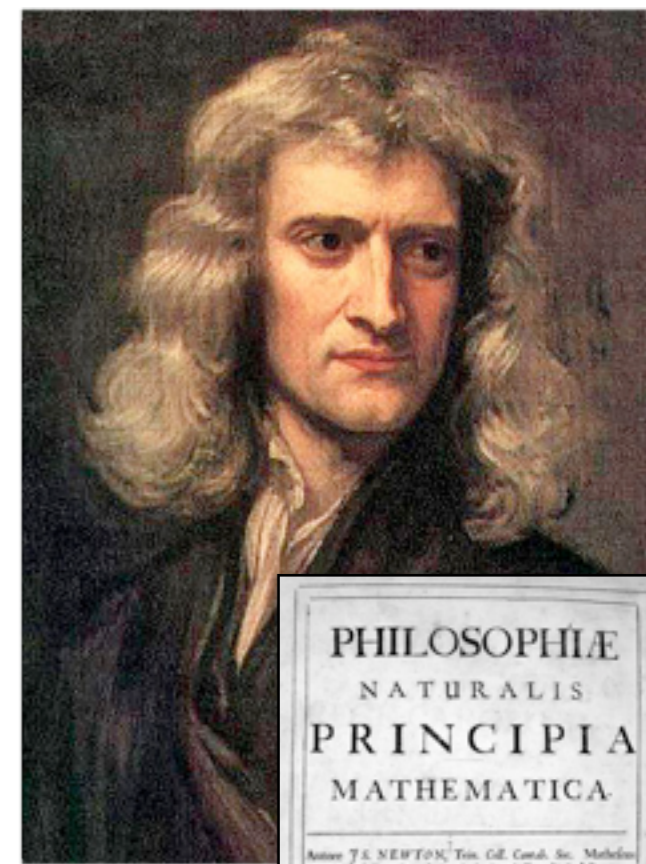
- equations of motion for  $N$  particles

$$\mathbf{F}_i = m_i \mathbf{a}_i = m_i \frac{d^2 \mathbf{r}}{dt^2} = m_i \ddot{\mathbf{r}}_i$$

- potential energy

$$U(\mathbf{r}_1, \dots, \mathbf{r}_N) = U_{\text{bonded}}(\{\mathbf{r}_i\}) + U_{\text{nonbonded}}(\{\mathbf{r}_i\})$$

source:Wikipedia



$$U_{\text{bond}}(\mathbf{r}_j, \mathbf{r}_k) = \frac{K}{2} (|\mathbf{r}_j - \mathbf{r}_k| - b_0)^2$$

$$U_{\text{angles}}(\mathbf{r}_i, \mathbf{r}_j, \mathbf{r}_k) \quad U_{\text{dih}}(\mathbf{r}_i, \mathbf{r}_j, \mathbf{r}_k, \mathbf{r}_l)$$

$$U_{\text{elec}}(\mathbf{r}_j, \mathbf{r}_k) = \frac{1}{4\pi\epsilon_0} \frac{q_j q_k}{|\mathbf{r}_j - \mathbf{r}_k|}$$

$$U_{\text{vdW}}(\mathbf{r}_j, \mathbf{r}_k) = 4\epsilon \left[ \left( \frac{\sigma}{r_{jk}} \right)^{12} - \left( \frac{\sigma}{r_{jk}} \right)^6 \right]$$

- forces

$$\mathbf{F}_i = -\nabla_i U(\mathbf{r}_1, \dots, \mathbf{r}_i, \dots, \mathbf{r}_N)$$

# Basic MD program

*initialize()*

$t=0$

while  $t < t_{\max}$

**$\mathbf{f} = \text{forces}(\mathbf{r})$**

**$\mathbf{r} = \text{integrate}(\mathbf{r}, \mathbf{f})$**

*write\_trajectory*( **$\mathbf{r}$** )

$t = t + dt$

# Basic workflow

1. prepare starting conformation
2. run equilibration
3. run production
  - compute estimators for observables  $a(\mathbf{r}, \mathbf{v})$
  - save trajectory ( $\mathbf{r}$ , maybe  $\mathbf{v}$  and  $\mathbf{F}$ )
4. analyse trajectory/output files

# Force calculation

*initialize()*

$t=0$

while  $t < t_{\max}$

**$\mathbf{f} = \text{forces}(\mathbf{r})$**

**$\mathbf{r} = \text{integrate}(\mathbf{r}, \mathbf{f})$**

**$\text{write\_trajectory}(\mathbf{r})$**

$t = t + dt$

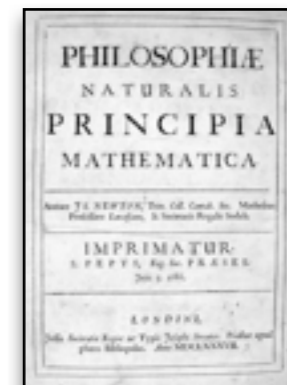
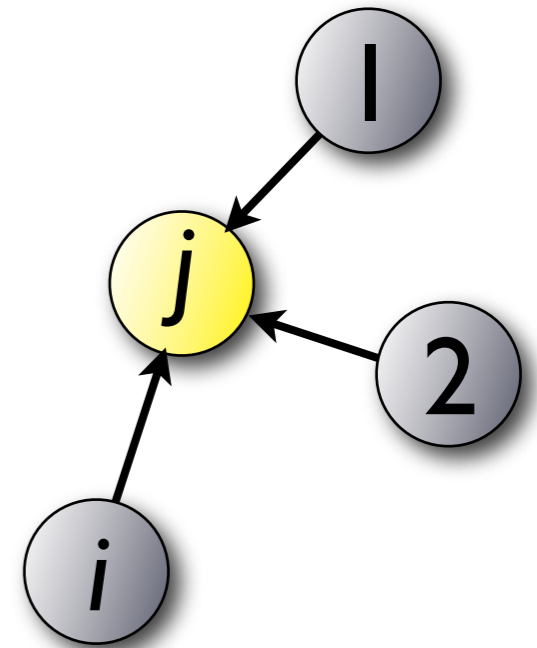
# Force calculation

$$\mathbf{F}_i = -\nabla_i U(\mathbf{r}_1, \dots, \mathbf{r}_i, \dots, \mathbf{r}_N)$$

For pair-potentials  $v(|\mathbf{r}_j - \mathbf{r}_i|) = v(r_{ij})$

$$\mathbf{F}_j = \sum_i \underbrace{[-\nabla_i v(r_{ij})]}_{\mathbf{f}_{ij}} = - \sum_i \frac{\mathbf{r}_{ij}}{r_{ij}} \frac{\partial}{\partial r_{ij}} v(r_{ij})$$

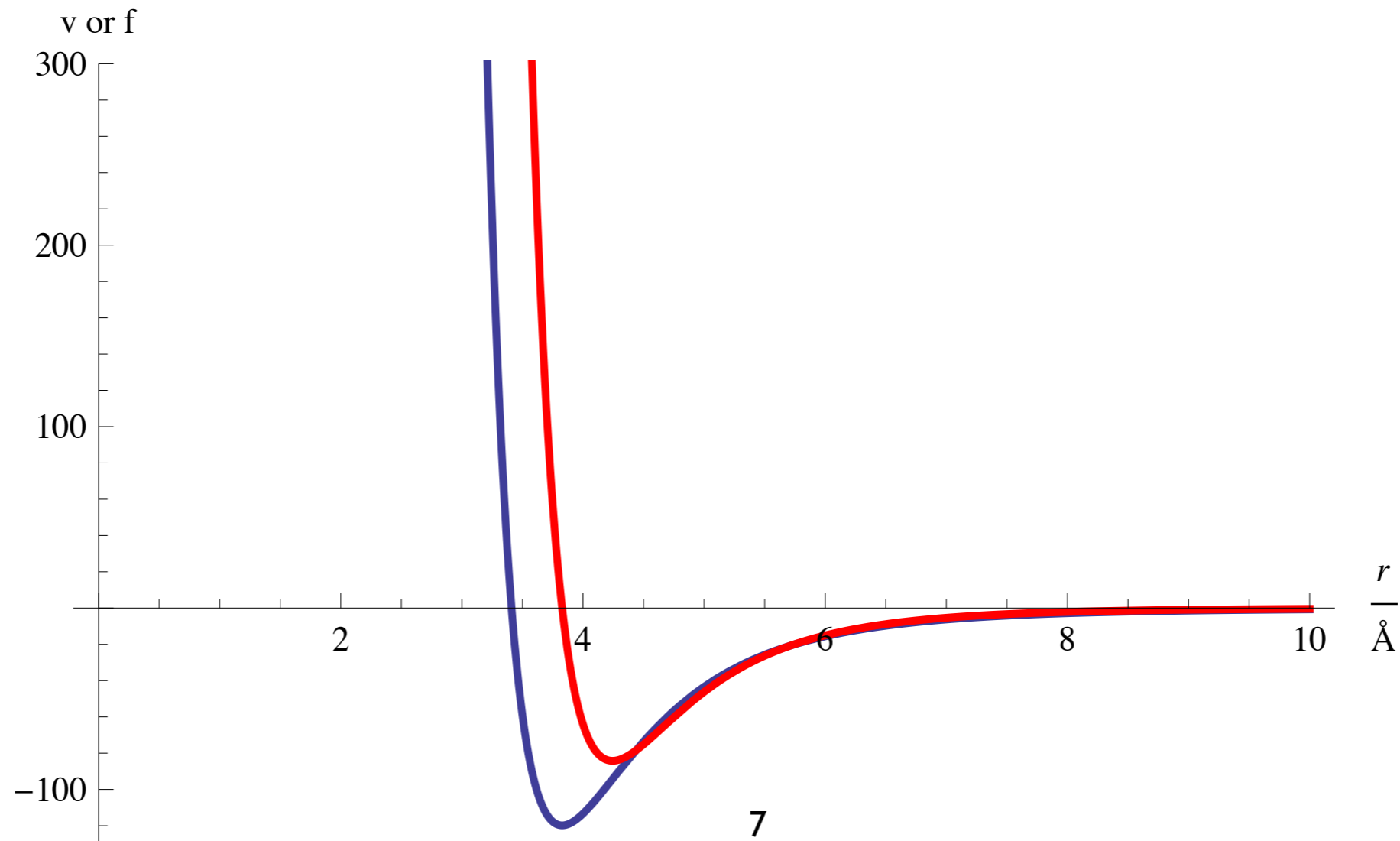
$$\mathbf{f}_{ij} = -\mathbf{f}_{ji} \quad (\text{Newton's 3rd law})$$



# Lennard-Jones Potential

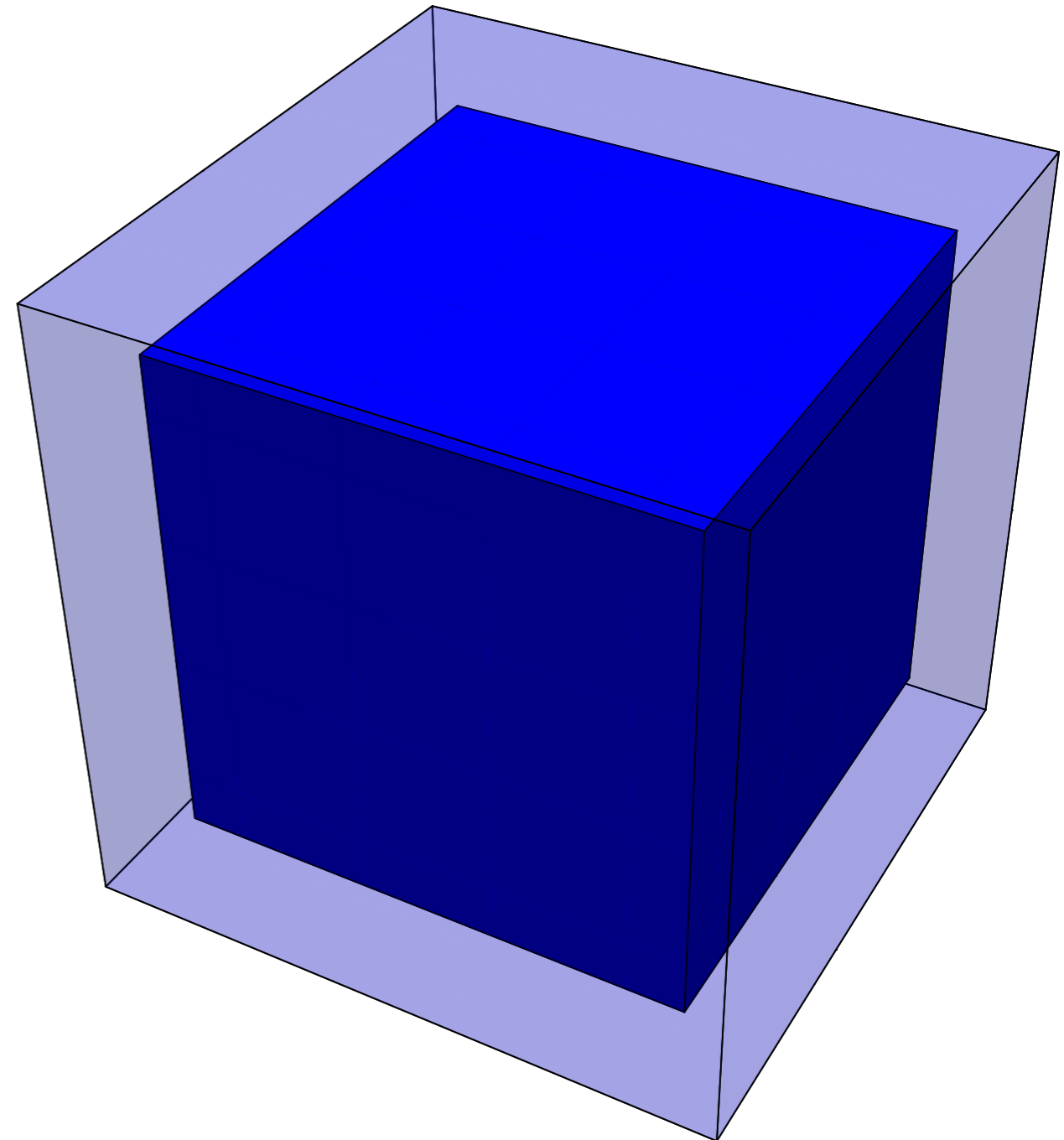
$$v(r_{ij}) = 4\epsilon \left[ \left( \frac{\sigma}{r_{ij}} \right)^{12} - \left( \frac{\sigma}{r_{ij}} \right)^6 \right]$$

$$\mathbf{f}(r_{ij}) = -24\epsilon \frac{\mathbf{r}_{ij}}{r_{ij}^2} \left[ 2 \left( \frac{\sigma}{r_{ij}} \right)^{12} - \left( \frac{\sigma}{r_{ij}} \right)^6 \right]$$



# Small systems: Surface effects

derive  $N_{\text{surf}}$  and the estimate;  
water 900 atoms in 30 Å box:  
almost 50% in surface

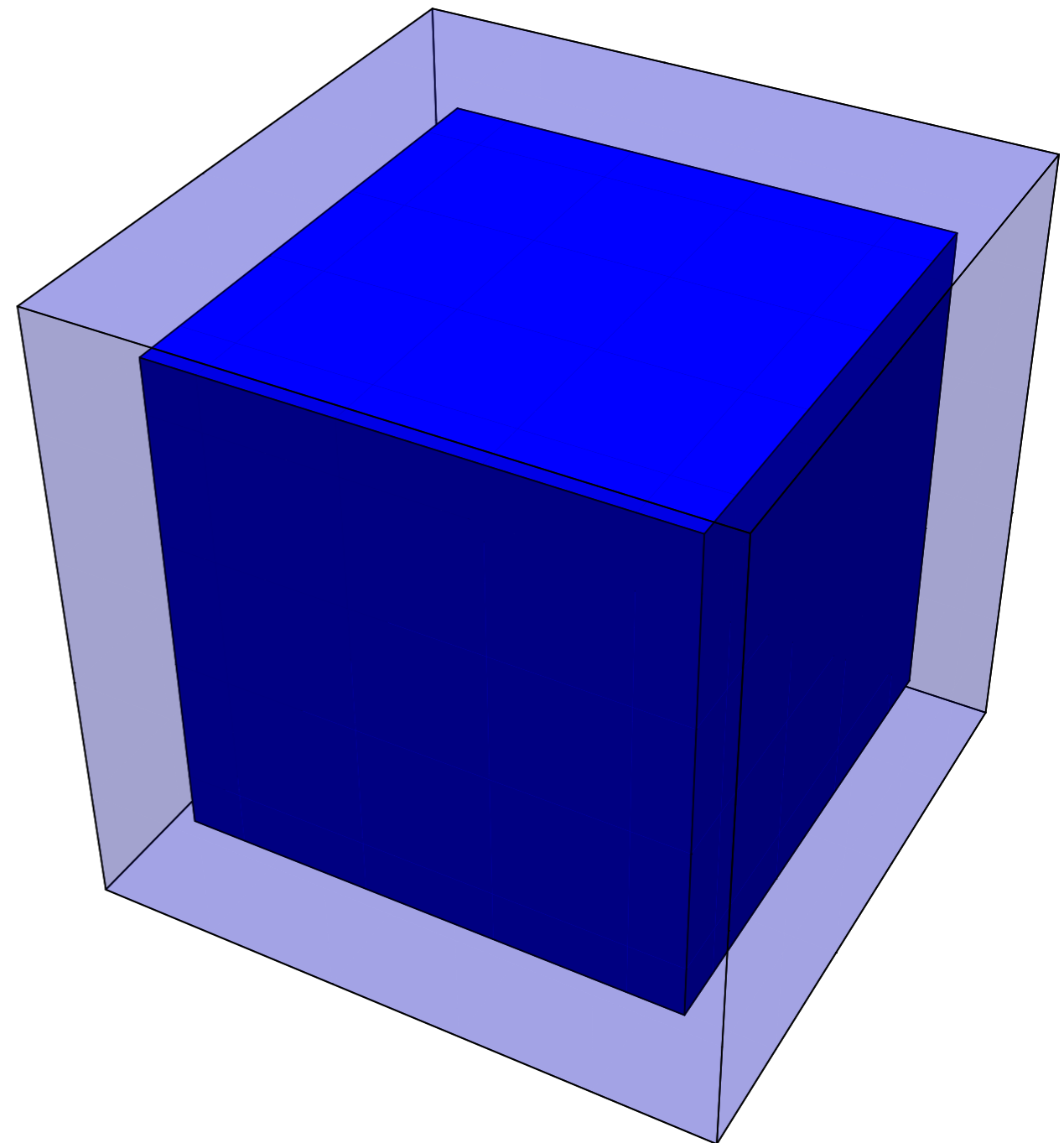




# Small systems: Surface effects

- In a small system, “most” particles are “near: the surface.

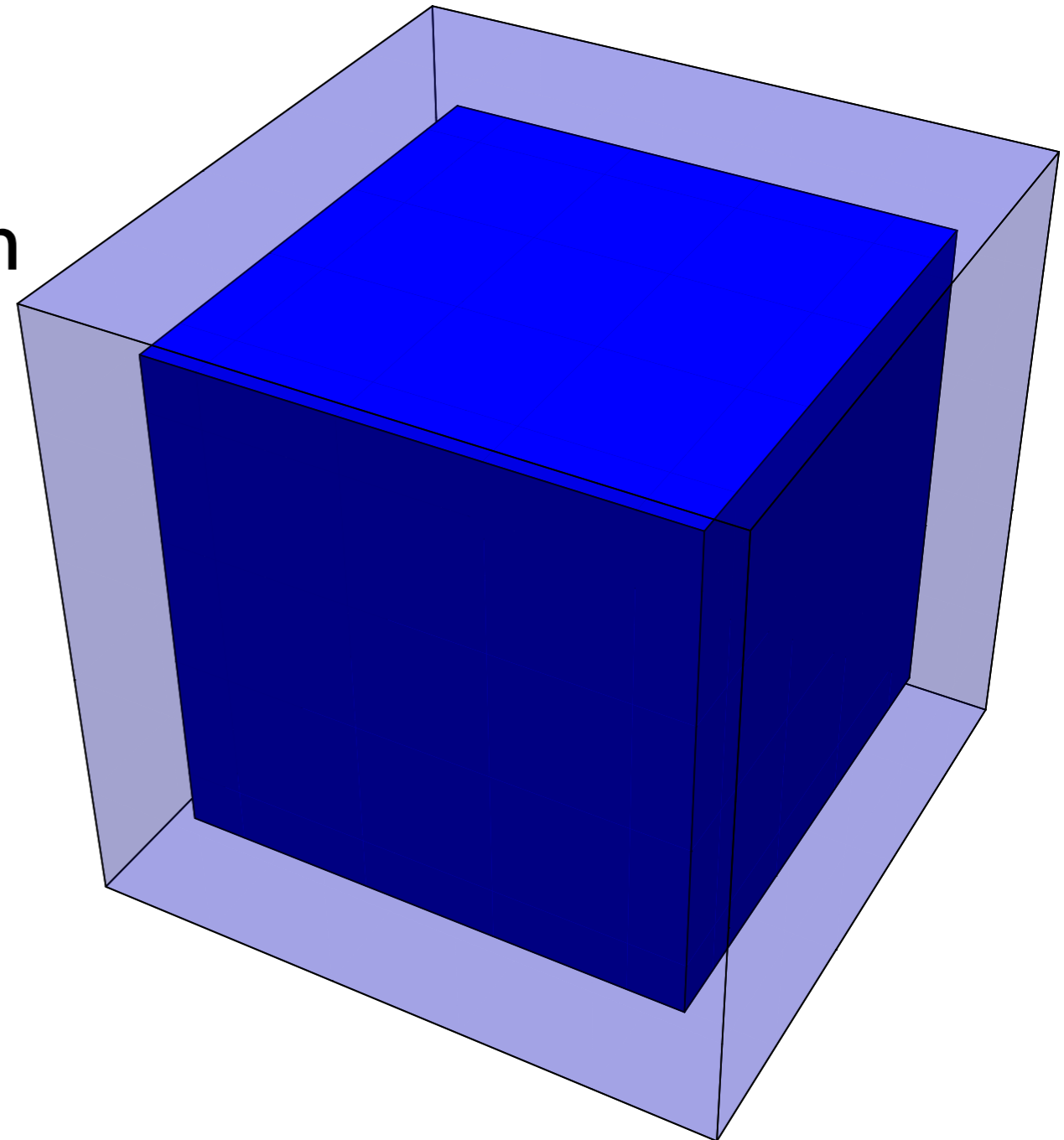
derive  $N_{\text{surf}}$  and the estimate;  
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# Small systems: Surface effects

- In a small system, “most” particles are “near: the surface.
- “near” = typical interaction distance  $d \sim 3\sigma$

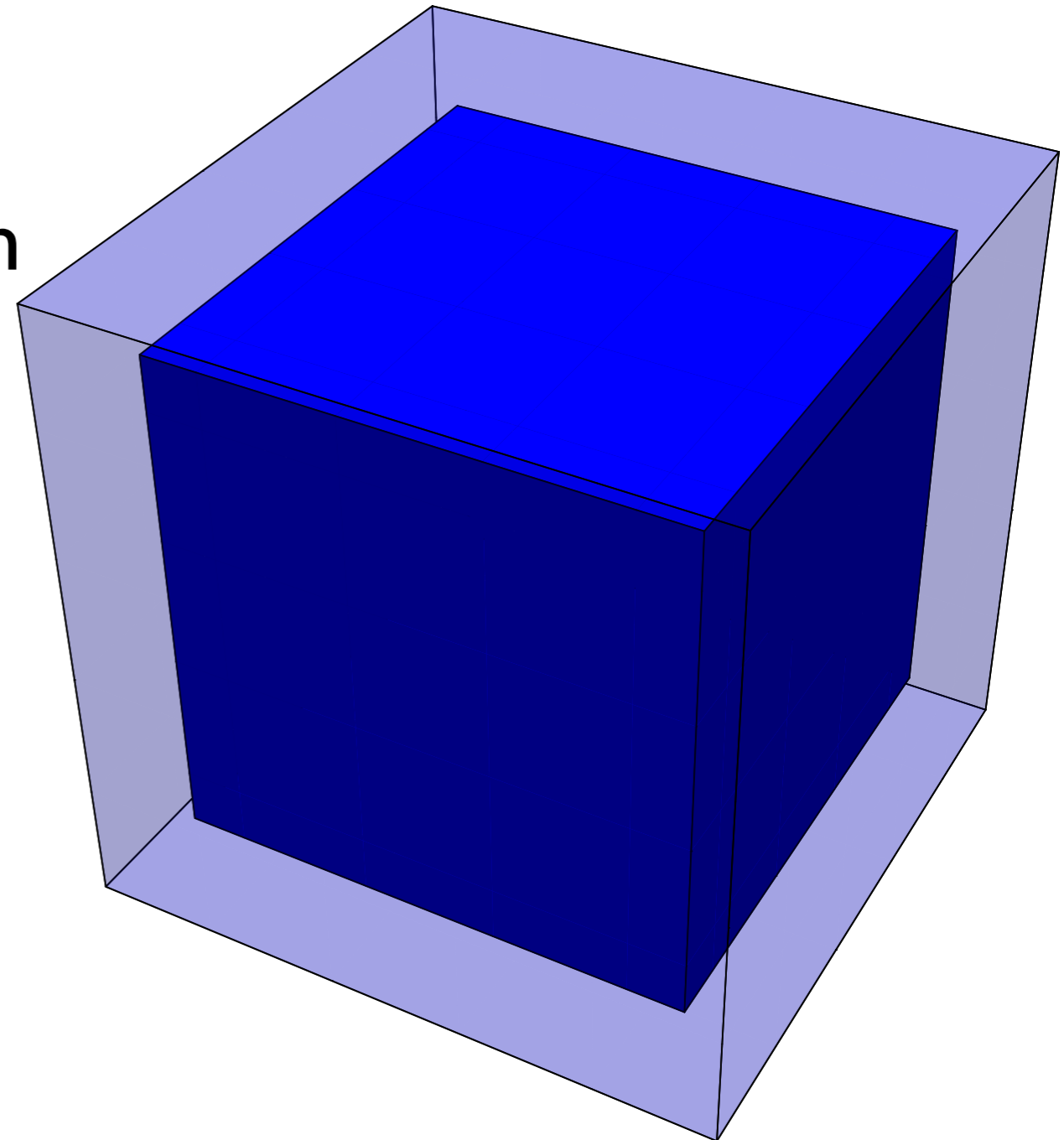
derive  $N_{\text{surf}}$  and the estimate;  
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# Small systems: Surface effects

- In a small system, “most” particles are “near: the surface.
- “near” = typical interaction distance  $d \sim 3\sigma$
- $N_{\text{surf}}/N \sim N^{-1/3}$

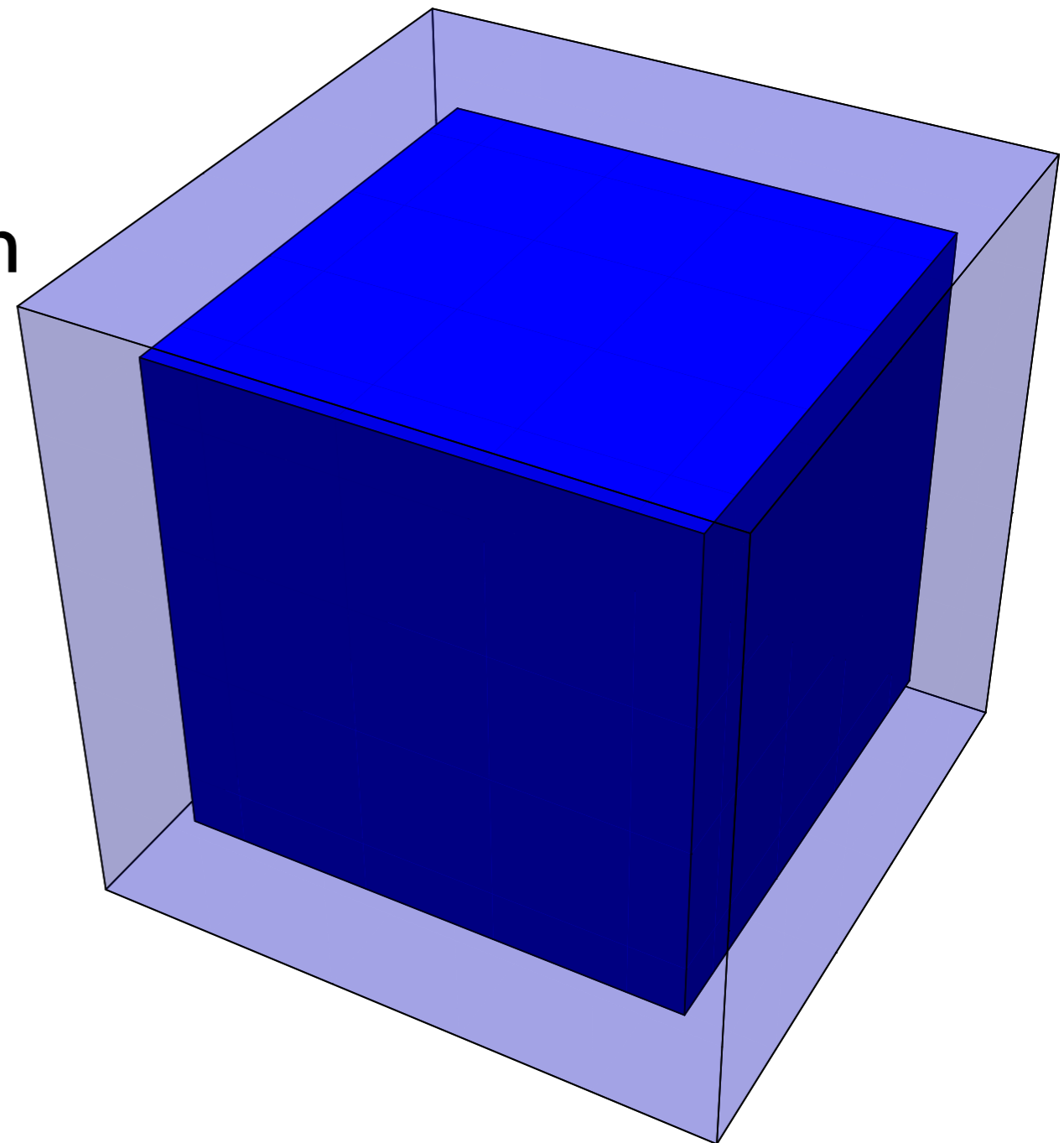
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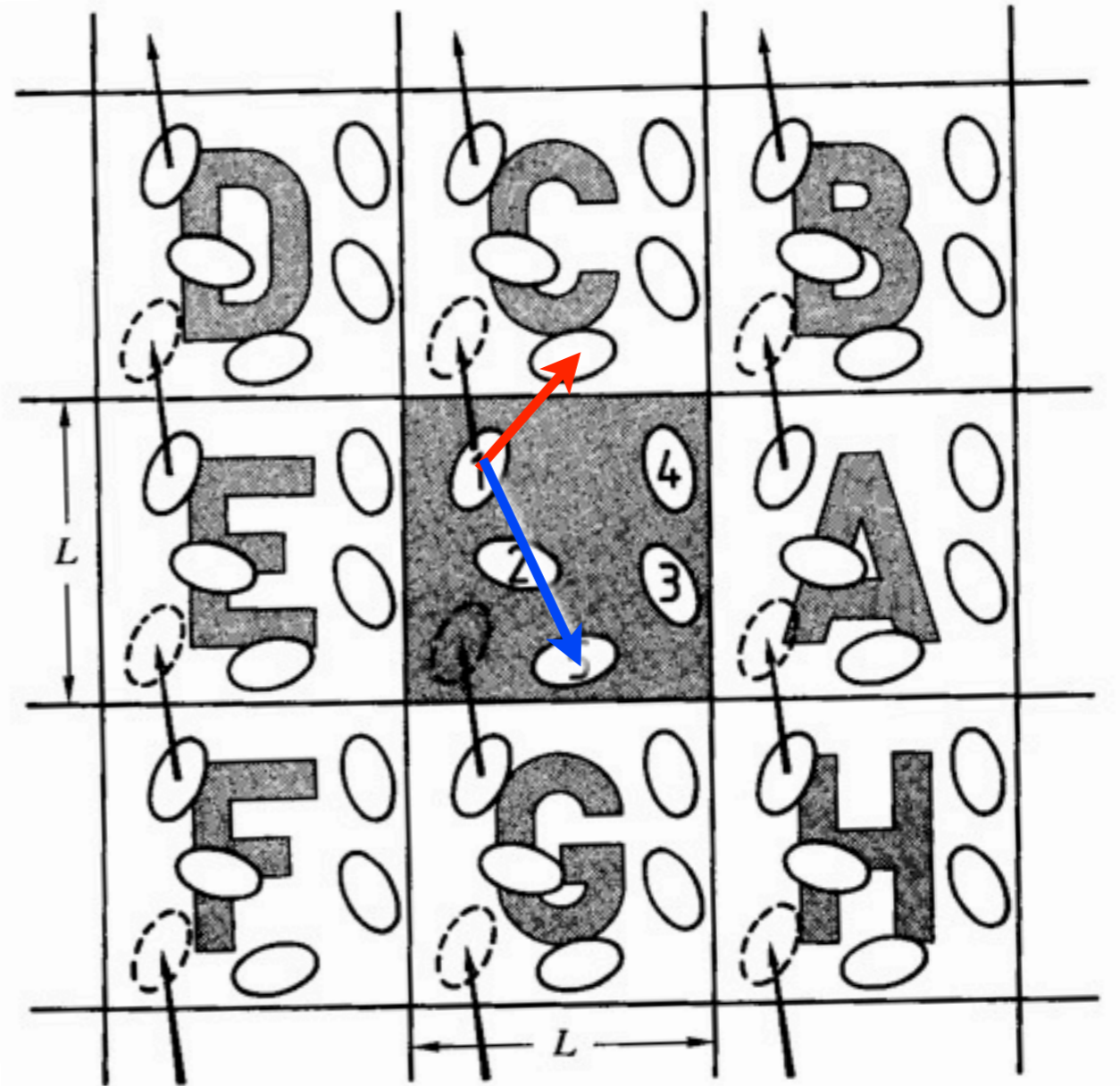
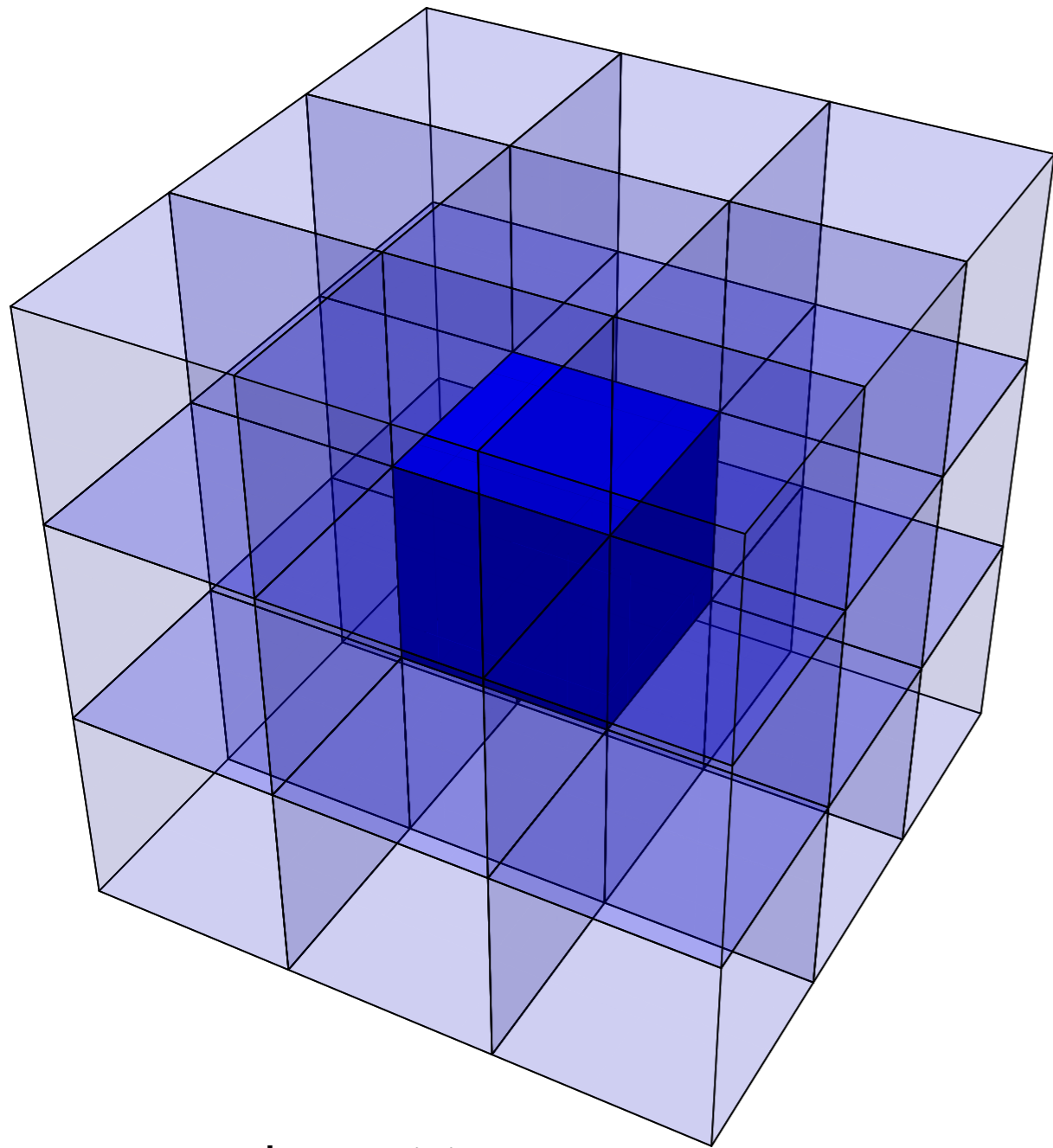
# Small systems: Surface effects

- In a small system, “most” particles are “near: the surface.
- “near” = typical interaction distance  $d \sim 3\sigma$
- $N_{\text{surf}}/N \sim N^{-1/3}$
- *Problem* when we are interested in **bulk properties**.

derive  $N_{\text{surf}}$  and the estimate;  
water 900 atoms in 30 Å box:  
almost 50% in surface



# Small systems: Periodic boundaries



box centered on origin:

$$\mathbf{r}_i \leftarrow \mathbf{r}_i - L \text{rint} \left( \frac{\mathbf{r}_i}{L} \right)$$

$$\mathbf{r}_{ij} \leftarrow \mathbf{r}_{ij} - L \text{rint} \left( \frac{\mathbf{r}_{ij}}{L} \right)$$

from Allen & Tildesley, 1987

# Periodic boundaries: Potential Issues

- simulate *infinite* system so must handle an infinite amount of interactions (though often truncation is permissible)
- spurious correlations/ordering
- only fluctuations allowed with lattice periodicity, and max wavelength  $\lambda=L$ 
  - ➔ phase transitions with long wavelength fluctuations problematic
- non-isotropic pair distribution function

... but generally works rather well!

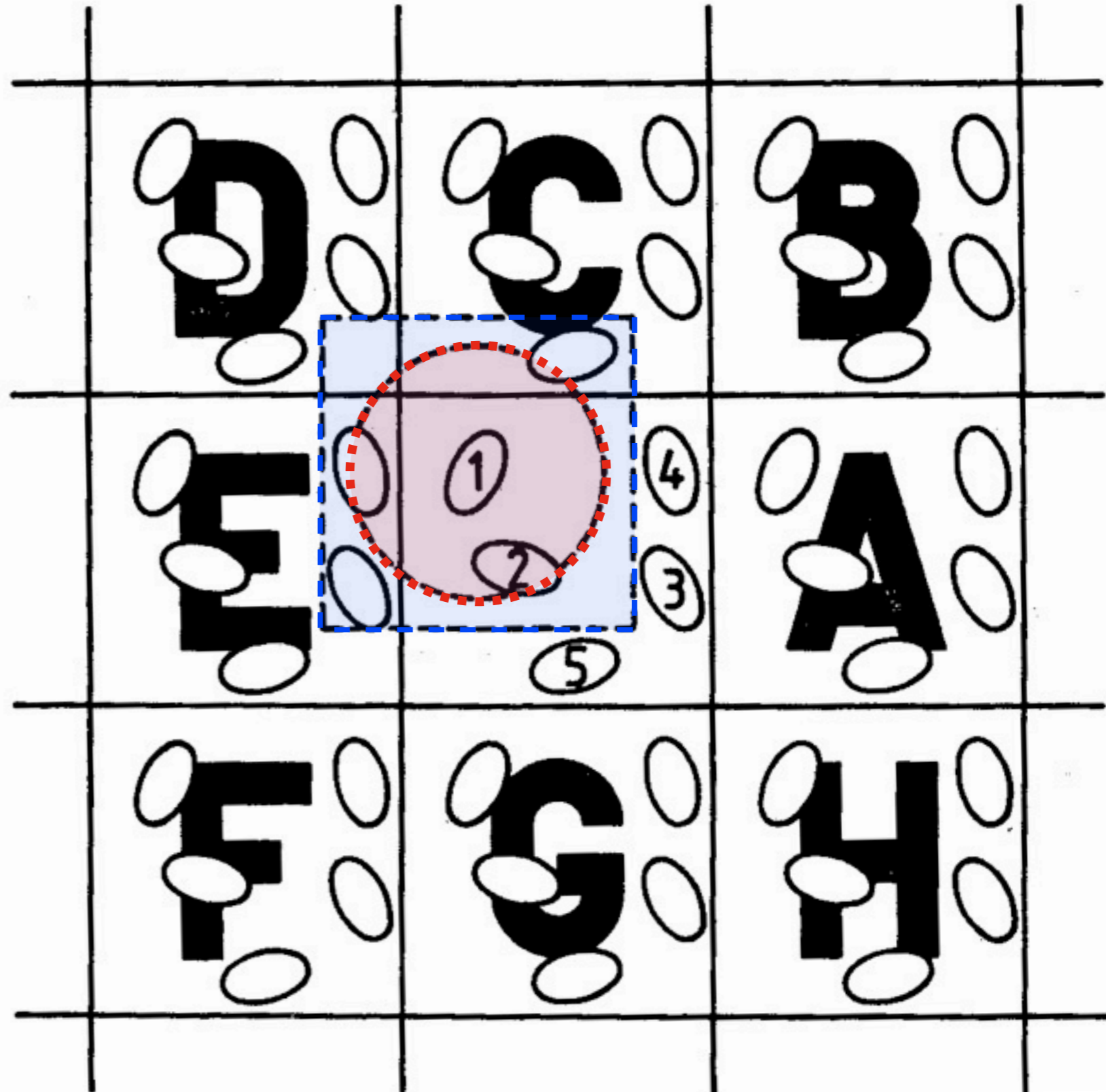


# Periodic boundaries: Interactions

- pair wise  $v(r_{ij}) \sim N^2$
- minimum image convention
- truncation at **cutoff  $R_c$**

$v(r)$  must fall off faster than  $r^{-3}$

$$R_c < L/2$$



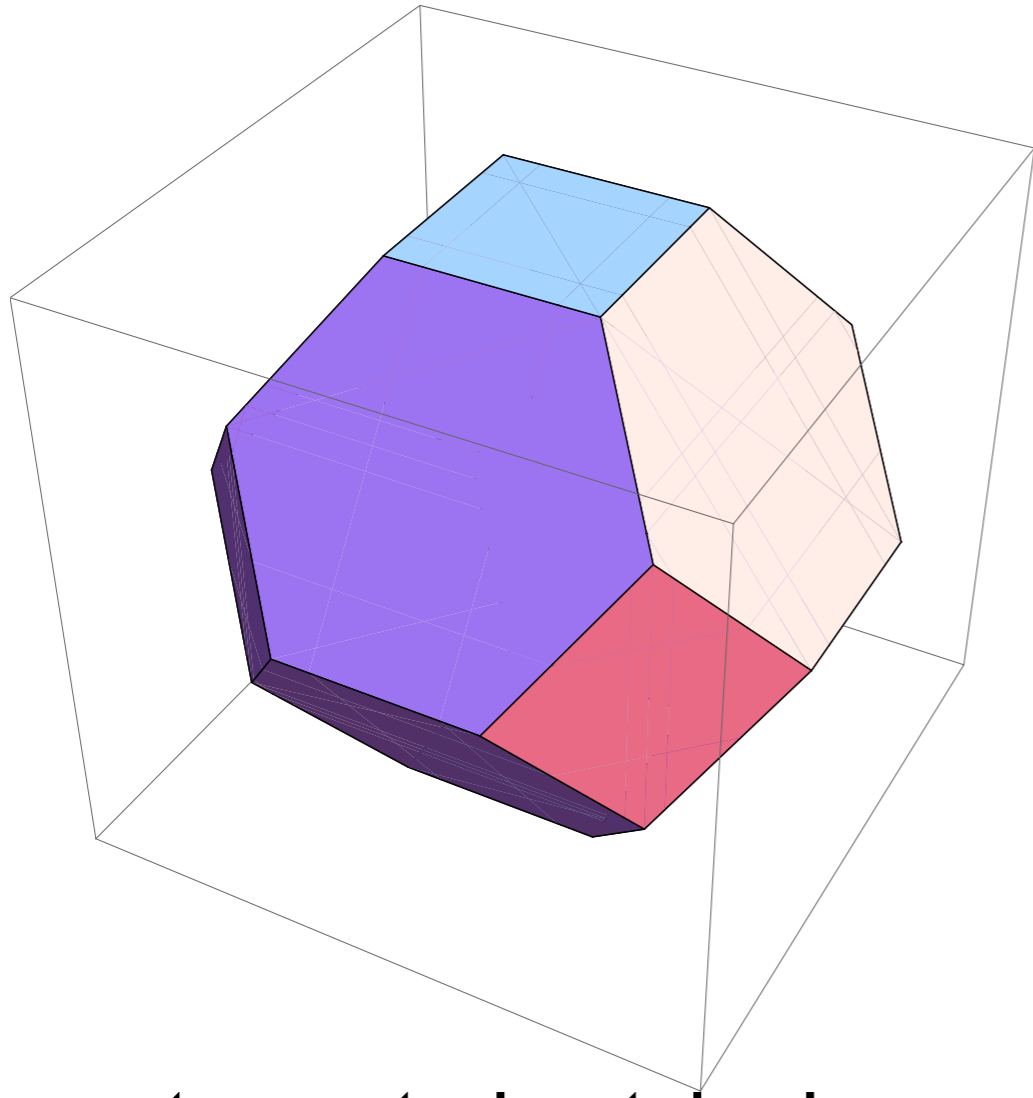
# Truncation of potentials

(proper periodic treatment: advanced topic)

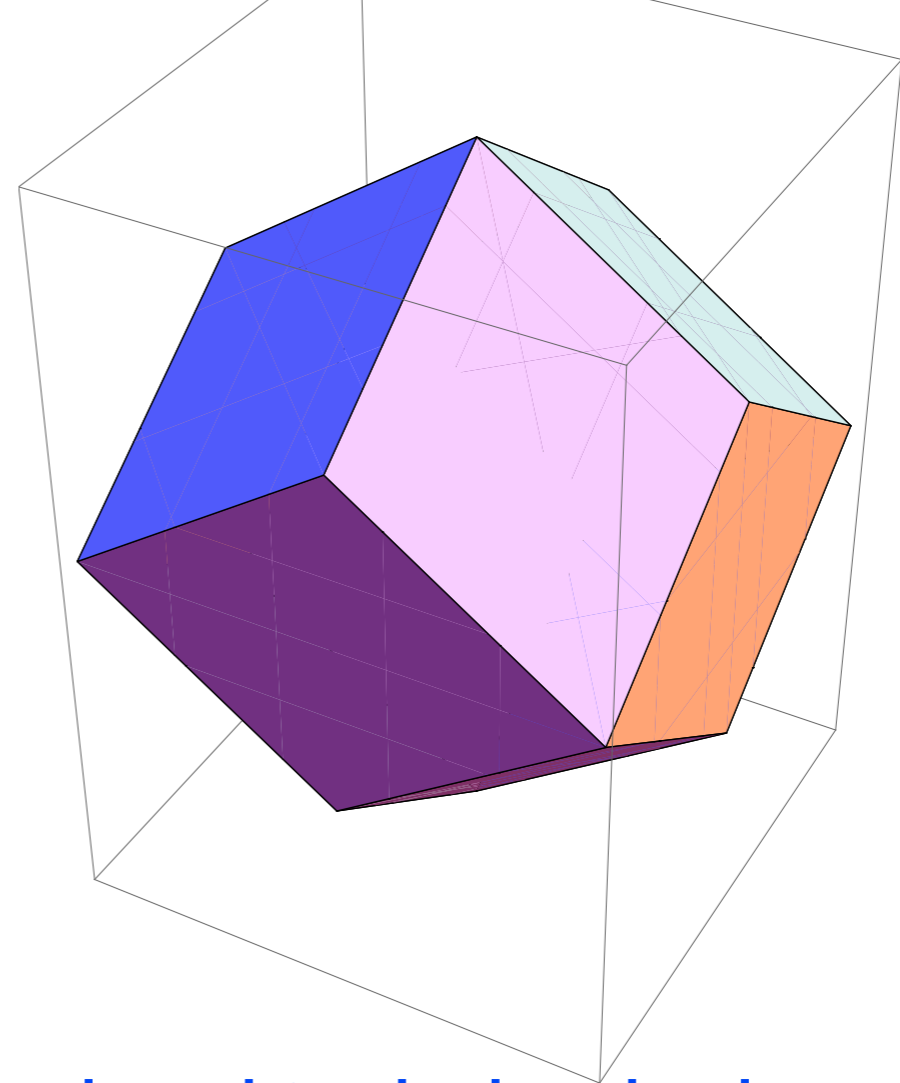
- simple truncation  $u^{\text{trunc}}(r) = \begin{cases} u(r) & r \leq R_c \\ 0 & r > R_c \end{cases}$
- truncation and shift  $u^{\text{shift}}(r) = \begin{cases} u(r) - u(R_c) & r \leq R_c \\ 0 & r > R_c \end{cases}$
- minimum image convention



# Periodic boundaries: Cells

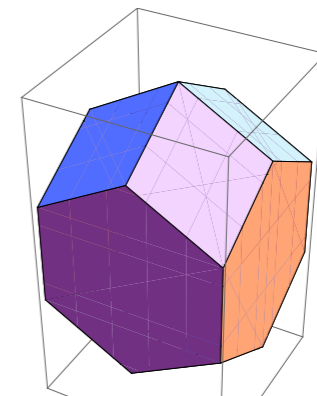
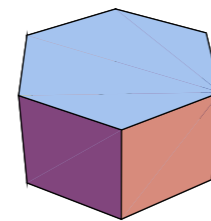
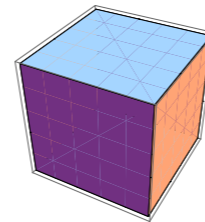


truncated octahedron  
( $0.77 d^3$ )



rhombic dodecahedron  
( $0.71 d^3$ )

- + cube/parallel epiped ( $d^3$ )
- + hexagonal prism
- + elongated rhombic dodecahedron



# Integrating the Equations of Motion

*initialize()*

$t=0$

while  $t < t_{\max}$

$\mathbf{f} = \text{forces}(\mathbf{r})$

$\mathbf{r} = \text{integrate}(\mathbf{r}, \mathbf{f})$

*write\_trajectory*( $\mathbf{r}$ )

$t = t + dt$

# Integrating the Equations of Motion

$$m_i \ddot{\mathbf{r}}_i = \mathbf{F}_i$$

- have forces  $\mathbf{F}_i$  and current positions  $\mathbf{r}_i(t)$
- want: positions  $\mathbf{r}_i(t+\Delta t)$

naïve scheme: *Euler*

$$\mathbf{r}(t + \Delta t) = \mathbf{r}(t) + \mathbf{v}(t)\Delta t + \frac{\mathbf{F}(t)}{2m}\Delta t^2 + \mathcal{O}(\Delta t^3)$$

...bad algorithm!

# Velocity Verlet Integrator

$$\mathbf{v}(t + \frac{\Delta t}{2}) = \mathbf{v}(t) + \frac{\Delta t}{2} \frac{\mathbf{F}(t)}{m} \quad (1)$$

$$\mathbf{r}(t + \Delta t) = \mathbf{r}(t) + \Delta t \mathbf{v}(t + \frac{\Delta t}{2}) \quad (2)$$

$$\mathbf{v}(t + \Delta t) = \mathbf{v}(t + \frac{\Delta t}{2}) + \frac{\Delta t}{2} \frac{\mathbf{F}(t + \Delta t)}{m} \quad (3)$$

- $\mathcal{O}(\Delta t^4)$
- gives both positions and velocities
- one force evaluation per time step

# Good integrators

- speed? – not very relevant
- accuracy for large time steps  $\Delta t$
- **energy conservation** (for  $\partial H/\partial t = 0$ )
  - short term
  - long term (more important)
- time reversible (Newton's EOMs!)
- phase-space area preserving (Hamiltonian dynamics!)
- accurately predict the trajectories of all particles for short and long times?

show energy conservation of  
Hamiltonian system

"built into" EOMs

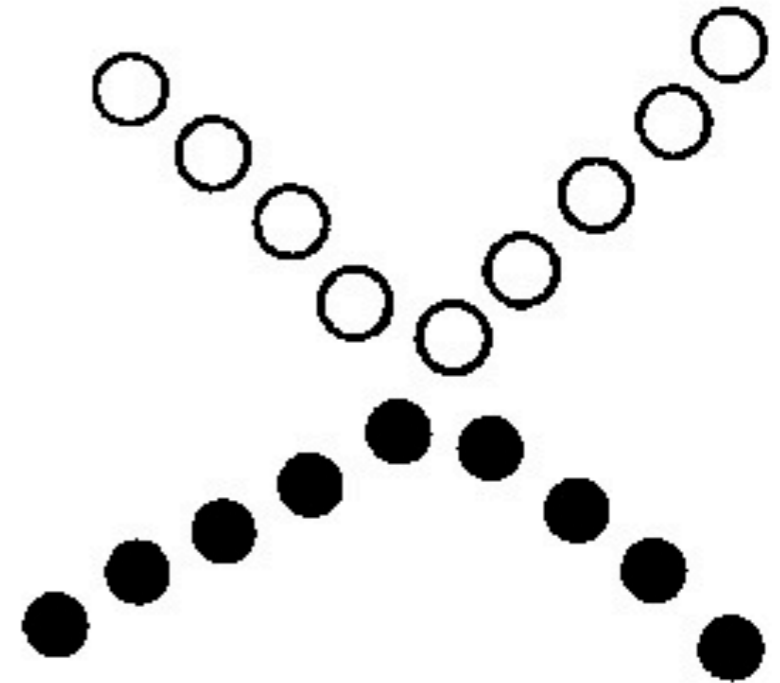
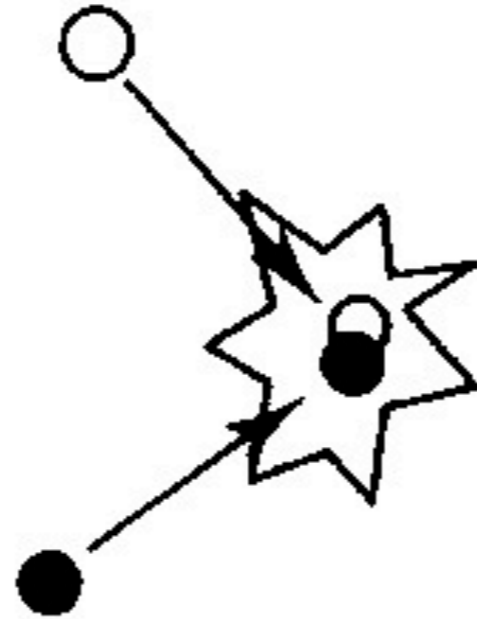
# Good integrators

- speed/memory? – not very relevant
- accuracy for large time steps  $\Delta t$
- energy conservation (for  $\partial H/\partial t = 0$ )
  - short term
  - long term (more important)
- time reversible (Newton's EOMs!)
- phase-space area preserving (Hamiltonian dynamics!)
- accurately predict the trajectories of all particles for short and long times?

# Verlet

- fast, small memory requirements
- not very high accuracy for long time steps
- fair short- and good long term energy conservation
- time reversible and area preserving (“symplectic”)

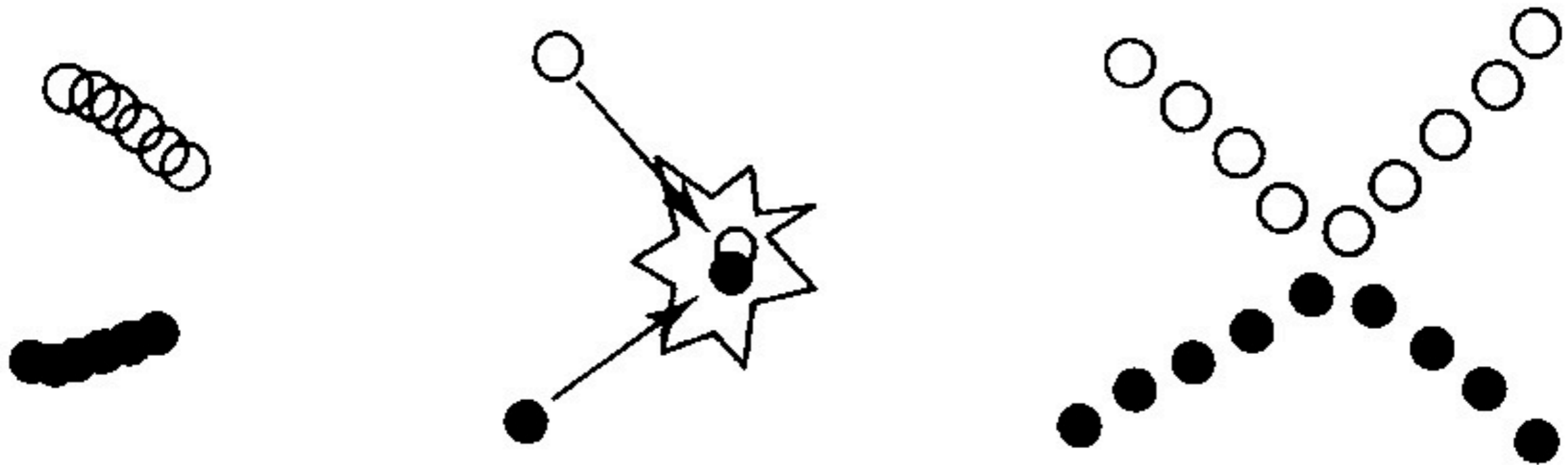
# Time step



*from Leach, 2001*



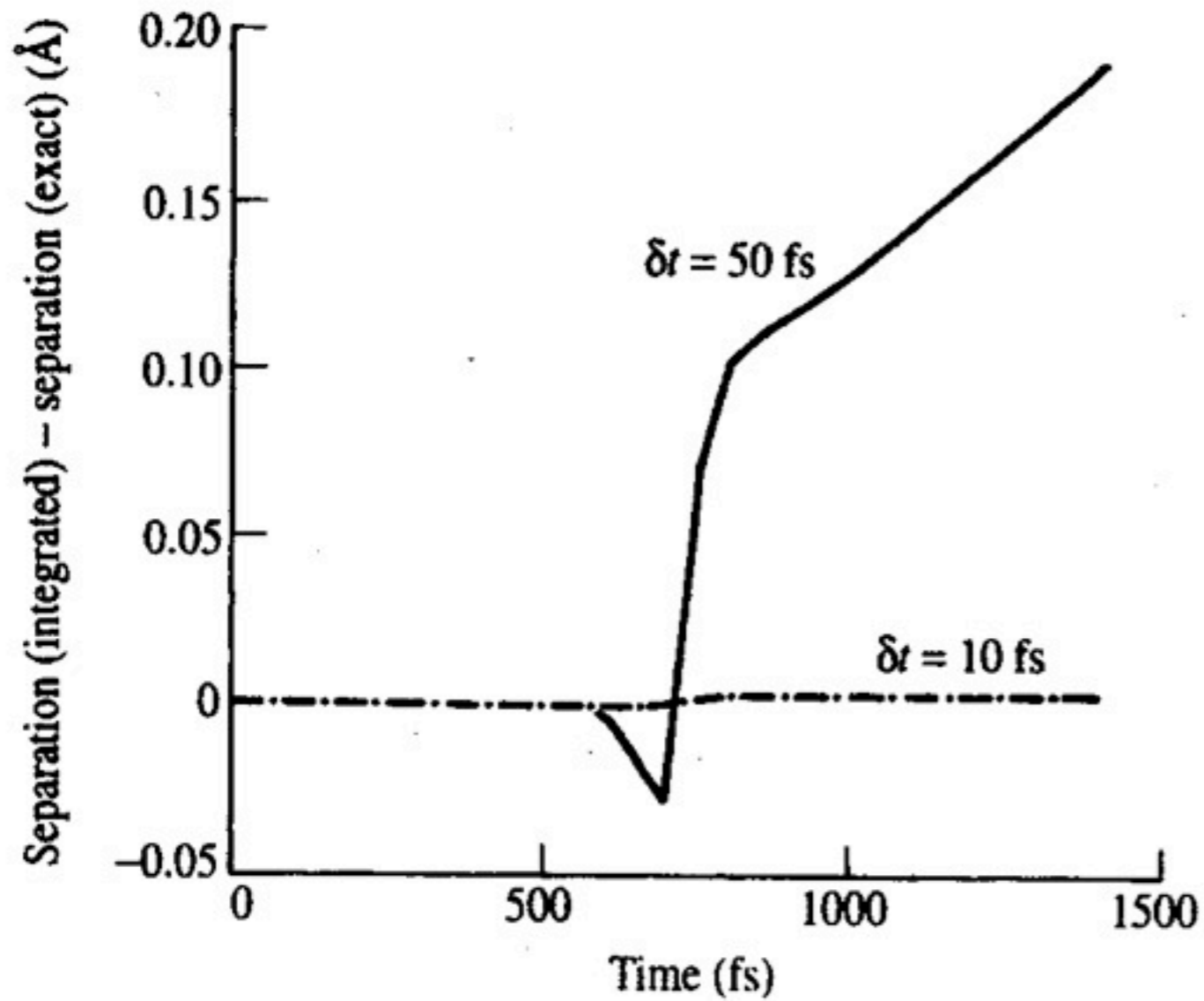
# Time step



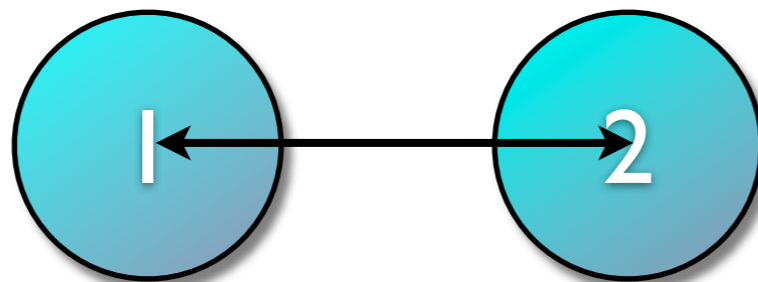
from Leach, 2001

- *rule of thumb for Verlet-type integrators: 5 steps per period (typically 1-2 fs in biomolecular systems)*

# Time step

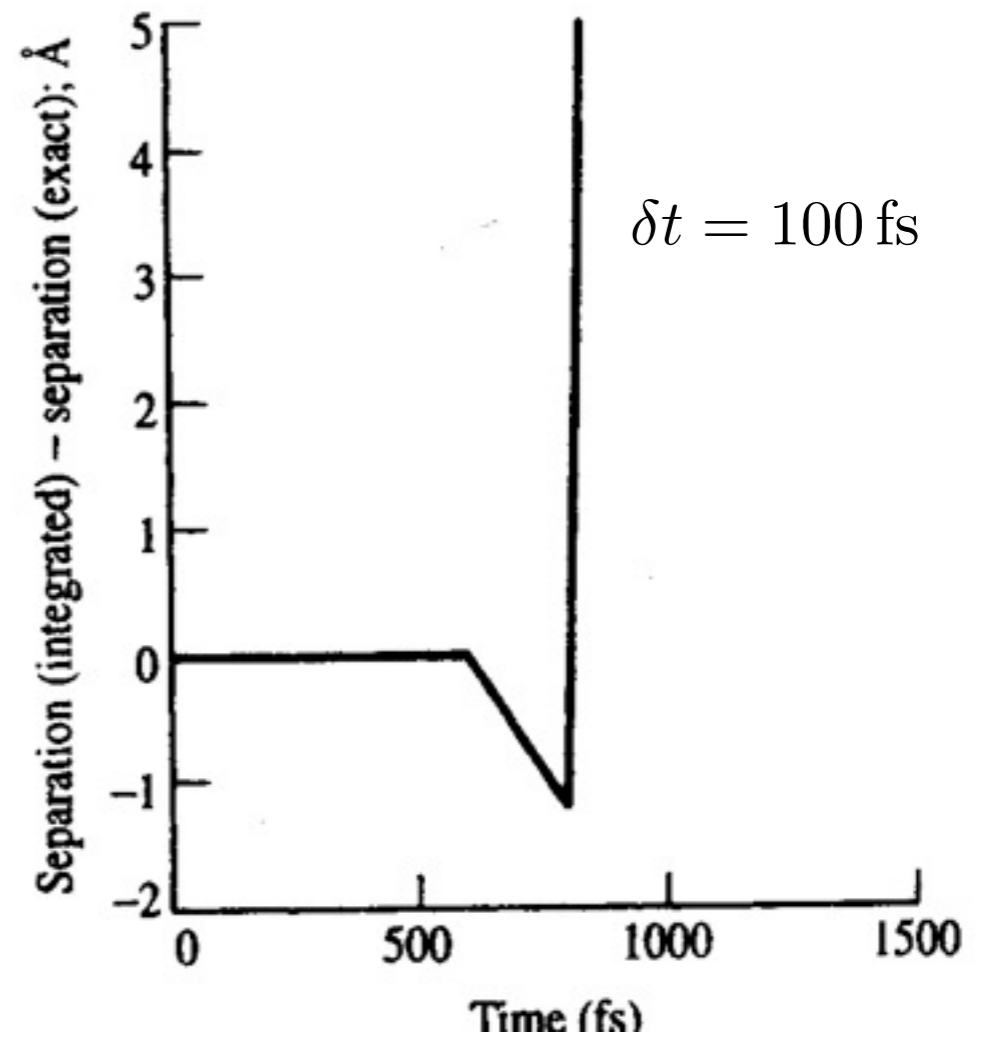
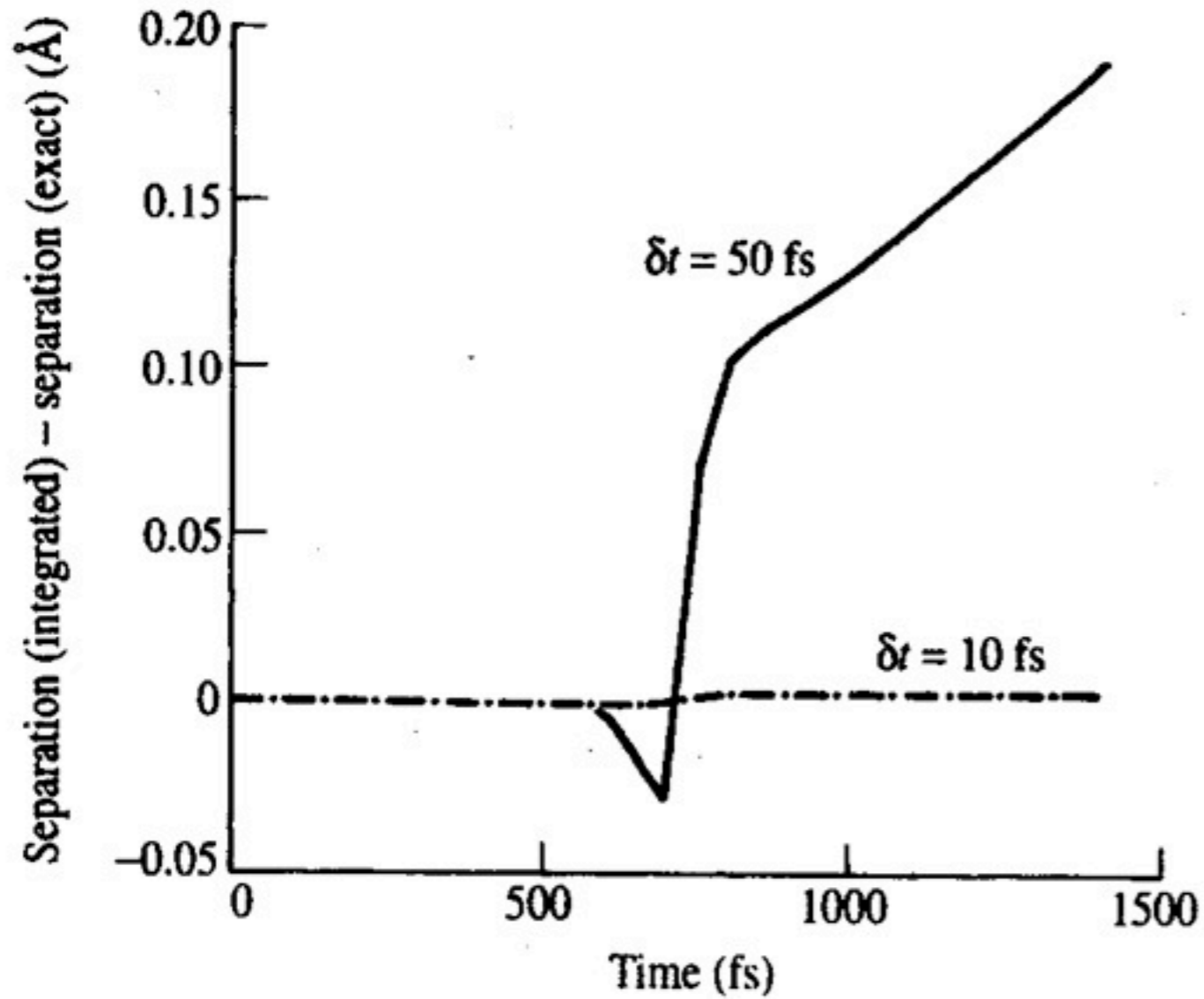


$\delta t = 100$  fs



from Leach, 2001

# Time step



from Leach, 2001

# Thermodynamic observables

- **Macroscopic thermodynamic quantities** (temperature  $T$ , pressure  $P$ , volume  $V$ , particle number  $N$ , heat capacities, dipole moments, magnetization, ...) can be written as **averages** over **functions that depend on microscopic positions and velocities** (“estimator”).

$$A = \langle a \rangle$$

$$A = \langle a(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N, \mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_N) \rangle$$

$$A = \langle a(\mathbf{x}_1(t), \mathbf{x}_2(t), \dots, \mathbf{x}_N(t), \mathbf{v}_1(t), \mathbf{v}_2(t), \dots, \mathbf{v}_N(t)) \rangle_t$$

$$A = \frac{1}{N_t} \sum_{i=1}^{N_t} a(\mathbf{x}_1(t), \mathbf{x}_2(t), \dots, \mathbf{x}_N(t), \mathbf{v}_1(t), \mathbf{v}_2(t), \dots, \mathbf{v}_N(t))$$

# Energy $E$

$$E = \langle \mathcal{H} \rangle$$

$$\mathcal{H} = T_{\text{kin}}(t) + U(t)$$

$$= \sum_{i=1}^N \frac{1}{2} m_i \mathbf{v}_i^2 + \sum_{i < j}^{N-1} U_{\text{LJ}}(r_{ij})$$

$$r_{ij} := |\mathbf{r}_j - \mathbf{r}_i|$$

$\mathcal{H}$ : “Hamiltonian” (total instantaneous energy)

Energy conservation:  $\frac{d\mathcal{H}}{dt} = 0$

# Temperature $T$

$$T_{\text{kin}}(t) = \frac{1}{2} \sum_{i=1}^N m_i \mathbf{v}_i(t)^2 \quad \langle T_{\text{kin}} \rangle = N \frac{3}{2} k_B T$$

1/2  $kT$  per degree of freedom

$$T = \frac{2 \langle T_{\text{kin}} \rangle}{3 k_B N}$$

**Boltzmann's constant**

$$k_B = 1.38064852 \times 10^{-23} \text{ J} \cdot \text{K}^{-1}$$

$$\mathcal{T}(t) = \frac{2T_{\text{kin}}(t)}{3k_B N}$$

$$T = \langle \mathcal{T}(t) \rangle_t$$

$$A = \frac{1}{N_t} \sum_{i=1}^{N_t} a(\mathbf{x}_1(t), \mathbf{x}_2(t), \dots, \mathbf{x}_N(t), \mathbf{v}_1(t), \mathbf{v}_2(t), \dots, \mathbf{v}_N(t))$$

# Pressure $P$

- pressure can be derived from a version of the *virial theorem* (... another time)

$$PV = Nk_B T + \frac{w}{3}$$

“virial”  $w := \left\langle \sum_{i < j}^{N-1} \mathbf{r}_{ij} \cdot \mathbf{f}_{ij} \right\rangle$        $\mathbf{F}_i = \sum_{j \neq i} \mathbf{f}_{ij}$

$$\mathcal{P}(t) = V^{-1} \left[ Nk_B \mathcal{T}(t) + \frac{1}{3} \sum_{i < j}^{N-1} \mathbf{r}_{ij}(t) \cdot \mathbf{f}_{ij}(t) \right]$$

$$P = \langle \mathcal{P}(t) \rangle_t$$

# Summary

- outline of the MD algorithm
- use of periodic boundary conditions
- potential truncation
- integrators
- calculating macroscopic observables from microscopic estimators



# Appendix

# Verlet Integrator

$$\mathbf{r}(t + \Delta t) \approx 2\mathbf{r}(t) - \mathbf{r}(t - \Delta t) + \frac{\mathbf{F}(t)}{m} \Delta t^2$$

- no velocities needed
- $\mathcal{O}(\Delta t^4)$
- velocities can be computed (but  $\mathcal{O}(\Delta t^2)$ )

derive from Taylor expansions of  $x(t+\Delta t)$  and  $x(t-\Delta t)$

$$\mathbf{v}(t) = \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t - \Delta t)}{2\Delta t} + \mathcal{O}(\Delta t^2)$$

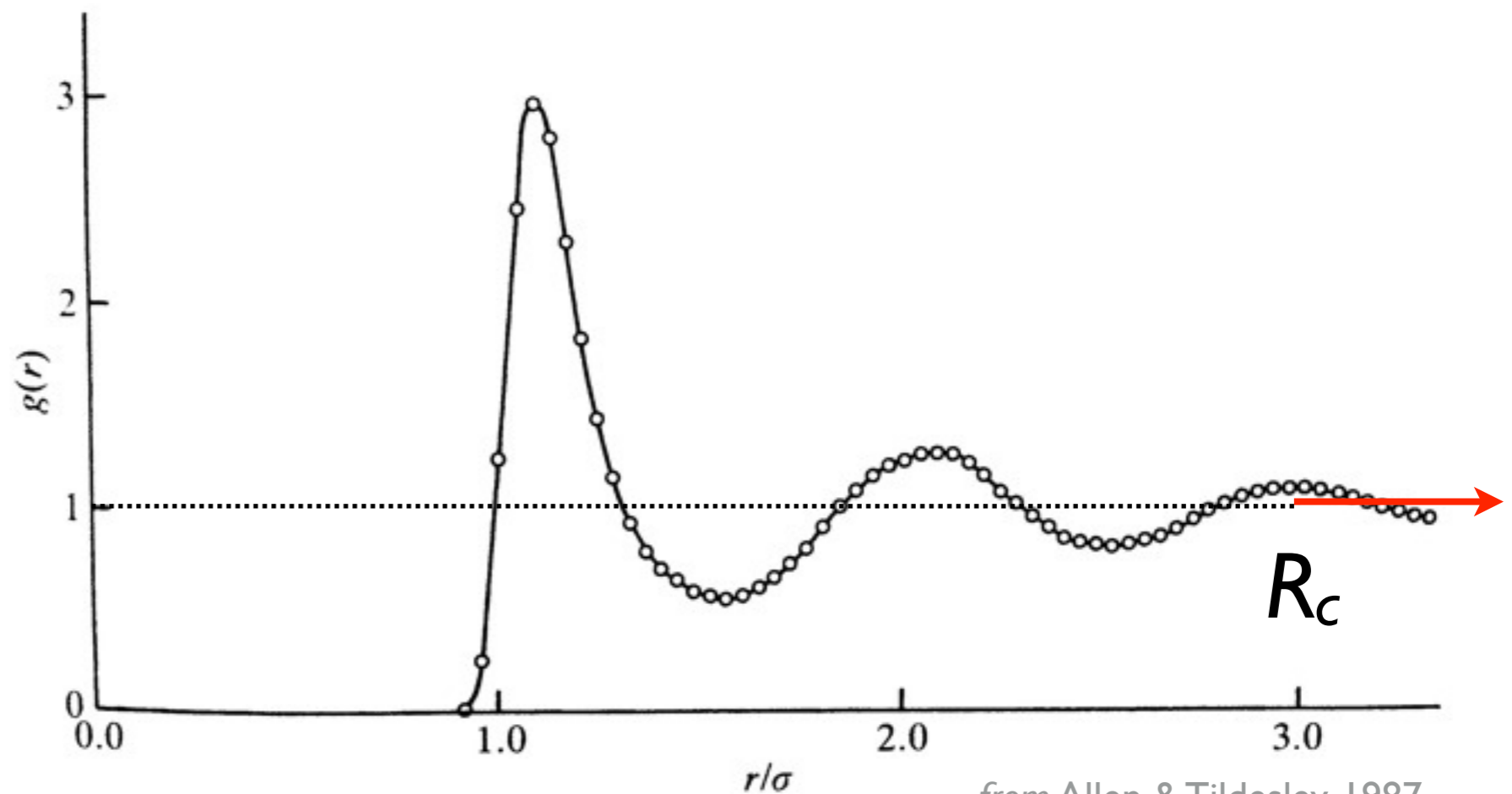
# Periodic boundaries: Tail correction

$$U_{\text{tot}} = \frac{1}{2} N \rho \int_0^{\infty} u(r) g(r) 4\pi r^2 dr$$

$$U_{\text{tot}} = \sum_{i < j} u_c(r_{ij}) + \frac{1}{2} N \rho \int_{R_c}^{\infty} u(r) 4\pi r^2 dr$$

$$g(r) \approx 1 \quad \text{for } \underline{r > R_c}$$

$$u_c(r) = \begin{cases} u(r) & r \leq R_c \\ 0 & r > R_c \end{cases}$$



tail correction for  $1/r$ ,  $1/r^2$ ,  $1/r^3$